#### **CELT Technical Note No. 5**

### **CELT Segment Positioning Actuators - Requirements**

Jerry Nelson March 2001

#### **Number of Actuators**

The current segmentation calls for 1080 segments plus (1080 / 6 =) 180 spare segments.

Three actuators per segment are used to control piston/tip/tilt of the segment.;  $3 * (1080 + 180) = 3780 + \text{spares} \Rightarrow \sim 4000 \text{ actuators}.$ 

Each actuator connects to the segment through a whiffletree used to more uniformly distribute the load to the segment.

## **Requirements** (Keck actuators are shown for comparison)

	Keck	CELT
Range	> 0.6 mm	> 1.2 mm
Rms position error averaged over 20	min < 20 nm	< 7 nm
Tracking rate 2	2 to 10 moves / sec	
Slew rate	$> 10 \ \mu \ / \ sec$	$> 10 \mu/sec$
Transverse load capacity	> 14 kg	> 5 kg
Axial load capacity	> 150 kg	> 30 kg
Axial stiffness	$> 5.9 \times 10^7 \text{ N/m}$	$> 1 \times 10^7 \text{ N/m}$ (~100 Hz resonance)
Transverse stiffness	$> 12.7 \times 10^5 \text{ N/m}$	1 x 10 <sup>5</sup> N/m
Local ave power dissipation	< 10 W	< 2 W
Lifetime	te	en ~ 30 nm moves / sec

continuously for 10 years

Survival temperature  $2 \pm 20$   $^{\rm o}{\rm C}$ 

Operating temperature  $2 \pm 8$   $^{\circ}$ C

Operating humidity 0 to 100% condensing

Electrical shock resistance yes

Dust protected yes

Easy Installation and Removal yes

# **Budget Goal**

Less than ~ \$2000 / actuator including electronics and cabling